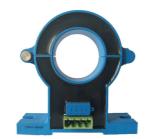


# Hall split core current sensor

Open loop split core type, Sub-plate installation, terminal output. Detect DC, AC and pulse current, High insulation between primary side and the vice side circuit.









Front view

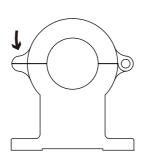
Back view

Fixed hole view Opening view

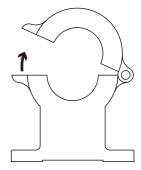
# Installation diagram

### Product features

- •Light weight
- •Low power consumption
- · Good linearity
- No insertion loss
- Fast response time
- Good anti-interference ability



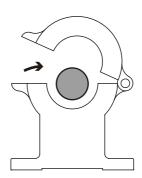
1.Loosen the screw



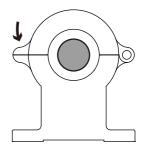
2.Open up

### Product application

- •Railway
- Metallurgical
- Welding machine
- Robot
- Motor
- •Inverter power supply
- Variable frequency governor



3.In the lead



4. Tighten the screws

•Uninterrupted power supply and communication power supply



# Electrical parameters: ( The following parameters are typical values and actual values will be subject to product testing )

### Remarks:

$I_{_{\mathrm{PN}}}$	Rated input	±200A	$\pm 500 \mathrm{A}$	±800A	±1000A	±1500A	±2000A	Standard input
Ipm	Input measurement range	±240A	$\pm 600 \mathrm{A}$	$\pm 960 \mathrm{A}$	$\pm 1200 \mathrm{A}$	$\pm 1800 \mathrm{A}$	±2400A	Default is 1.2 times of rated input
Vout	Rated output	$2.5V \pm 0.625V$						Standard output
X	Accuracy	1 %						$I = I_{PN}$
εL	Linearity	1 %						$I=0^{\sim} \pm I_{PN}$
Vс	Supply voltage	+5 V						Supply voltage range±5%
Ιc	Current consumption	≤16mA						Reference will be subject to the measured
R1	Load impedance	≥10K Ω						Collection port impedance while lower voltage affect accuracy
Voe	Zero offset voltage	$\leq \pm 15 \mathrm{mV}$						TA=25°C
Tr	Response time	≤5 μ s						Reference will be subject to the measured
N.w	Weight	306g						Reference will be subject to the measured
Та	Operation temperature	-10 ~+70 °C						
Ts	Storage temperature	-25~+70°C						
Bw	Band width	${\tt DC}^{\sim}25{\tt KHz}$					Factory test according to DC	
Vd	Delectric strength	2.5KV 50Hz 1min						

### Factory commissioning:

Calculation formula: 2.5V±0.625V 0V datum

- 1. Debugging with 0V as the reference point(acquiescence) Forward direction: 2.5+  $(I/I_{_{PN}})$  \*0.625
- 2. Debug with Vref as the reference point(optional) Reverse direction:  $2.5-(1/I_{PN})$  \*0.625

#### Instructions for use:

- 1. According to the connection mode of correct connection
- 2. The direction shown by the arrow is positive
- 3. With hole measurement, response time and following the speed for the best
- 4. Faulty wiring can lead to product damage and output uncertainty

#### Safe operation:

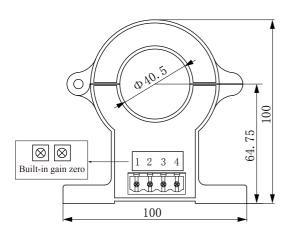
- \*Please read this specification carefully before use.
- \*When you need to move the product, please be sure to disconnect the power and all the connected cables.
- \*If found shell, devices attached to the fixed parts, wire, or have any damaged, please immediately deal with hidden dangers.
- \*If there is any doubt about the safe operation of the equipment, the equipment and the corresponding accessories should be closed immediately, and the fastest time for troubleshooting.

#### Proclamations:

As our products are constantly being improved and updated, we reserve the right to modify the content of this specification at any time without prior notice.



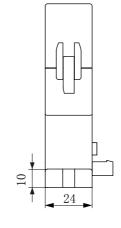
#### Dimensions (in $mm\pm0.5$ ):

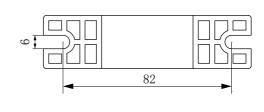


Front view

#### Current direction

Print surface **←** Epoxy surface





Side view

Bottom view

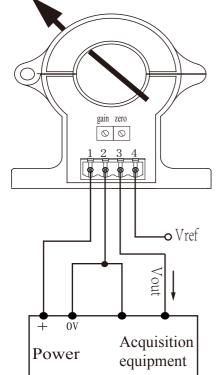
## Connector Illustration





Wiring diagram (based on 0 V)

Crimping terminal fast plug 2EDG-5.08-4p spacing 5.08mm



## Terminal definition:

1: +V

2: 0V

3: Vout

4: Vref (Can be suspended, not grounded)

# Potentiometer definition:

Left: gain

right: zero

### **X** Detection:

- ①Choose the auxiliary power supply with small ripple ( $\leq 10 \text{mV}$ )
- ②Switch on auxiliary power
- (3) The auxiliary power is connected to the sensor
- 4 The sensor detects the primary current