

# Hall open loop current sensor

sub-plate mount, terminal output. Detect DC, AC and pulse current, High insulation between primary side and the vice side circuit.







Front view

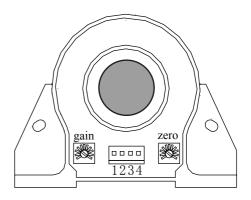
Epoxy view

Fixed hole view

### Product features

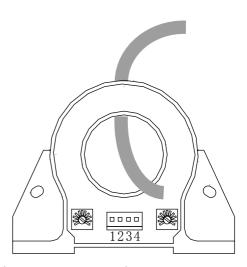
- ·Light weight
- •Low power consumption
- Good linearity
- No insertion loss
- Fast response time
- Good anti-interference ability

# Installation diagram



### Product application

- Railway
- Metallurgical
- Welding machine
- Robot
- Motor
- •Inverter power supply
- Variable frequency governor
- •Uninterrupted power supply and communication power supply





# $Electrical\ parameters: \ (\ \ \ The\ following\ parameters\ are\ typical\ values\ and\ actual\ values$

Ele	Electrical parameters: ( The following parameters are typical values and actual values will be subject to product testing )							Remarks:
$I_{PN}$	Rated input	±100A	±200A	±300A	±400A	±500A	$\pm600$ A	Standard input
Ipm	Input measurement range	$\pm150\text{A}$	$\pm 300 \mathrm{A}$	$\pm450\mathrm{A}$	$\pm600$ A	$\pm750$ A	$\pm900$ A	Default is 1.5 times of rated input, and maximum ≤1000A (saturation)
Vout	Rated output	$\pm4\mathrm{V}$						Standard output
X	Accuracy	1 %						$I = I_{PN}$
εL	Linearity	1 %						$I=0^{\sim} \pm I_{PN}$
Vс	Supply voltage	$\pm$ 12V/ $\pm$ 15V						One or the other Supply voltage range±5%
Ιc	Current consumption	$\leqslant$ $\pm$ 15mA						Reference will be subject to the measured
R1	Load impedance	≥10KΩ						Collection port impedance while lower voltage affect accuracy
Voe	Zero offset voltage	$\leq \pm 15 \mathrm{mV}$						TA=25°C
Tr	Response time	≤5 μ s						Reference will be subject to the measured
N.w	Weight	215g						Reference will be subject to the measured
Та	Operation temperature	$-10$ $\sim$ $+70$ $^{\circ}$ C						
Ts	Storage temperature	$-25\sim$ $+70^{\circ}\mathrm{C}$						
Bw	Band width	$\mathtt{DC}^{\sim}\mathtt{10KHz}$						Factory test according to DC

6KV 50Hz 1min

#### Instructions for use:

Delectric strength

- 1. According to the connection mode of correct connection
- 2. The direction shown by the arrow is positive
- 3. With hole measurement, response time and following the speed for the best
- 4. Faulty wiring can lead to product damage and output uncertainty

#### Safe operation:

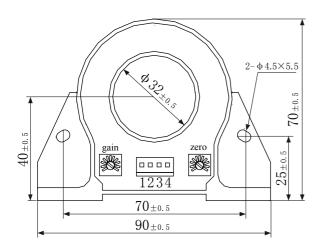
- \*Please read this specification carefully before use.
- \*When you need to move the product, please be sure to disconnect the power and all the connected cables.
- \*If found shell, devices attached to the fixed parts, wire, or have any damaged, please immediately deal with hidden dangers.
- \*If there is any doubt about the safe operation of the equipment, the equipment and the corresponding accessories should be closed immediately, and the fastest time for troubleshooting.

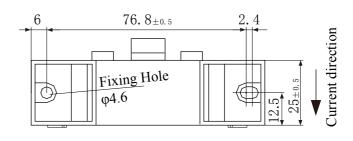
#### Proclamations:

As our products are constantly being improved and updated, we reserve the right to modify the content of this specification at any time without prior notice.



#### Dimensions (in $mm\pm0.5$ ):

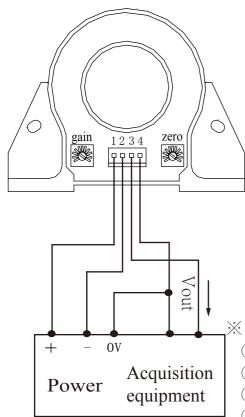




Front view

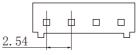
Bottom view

### Wiring diagram



### Connector Illustration:





Spacing 2.54 mm

# Terminal definition:

1: +V

2: -V

3: Vout

4: 0V

# Potentiometer definition:

left: gain

right: zero

#### × Detection:

- ①Choose the auxiliary power supply with small ripple ( $\leq 10$ mV)
- ②Switch on auxiliary power
- 3 The auxiliary power is connected to the sensor
- (4) The sensor detects the primary current