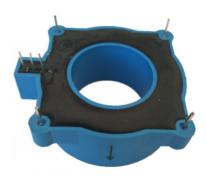


# Hall open loop current sensor

PCB mounting, Detect DC, AC and pulse current, High insulation between primary side and the vice side circuit.







Front view

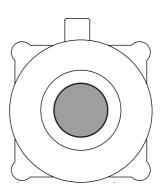
Epoxy view

Bottom view

#### Product features

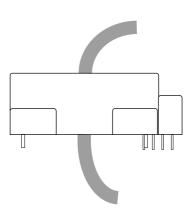
- ·Light weight
- •Low power consumption
- Good linearity
- No insertion loss
- Fast response time
- Good anti-interference ability

# Installation diagram



# Product application

- Railway
- Metallurgical
- Welding machine
- Robot
- Motor
- •Inverter power supply
- · Variable frequency governor
- •Uninterrupted power supply and communication power supply





# Electrical parameters: ( The following parameters are typical values and actual values will be subject to product testing )

### Remarks:

I	Rated input	±200A	±400A	$\pm600$ A	±800A	Standard input
Ipm	Input measurement range	±300A	±600A	±900A	±1200A	Default is 1.5 times of rated input, and maximum ≤1200A (saturation)
Vout	Rated output	$2.5V \pm 1.25V$				Standard output
X	Accuracy	1 %				$I = I_{PN}$
εL	Linearity	1 %				$I=0^{\sim} \pm I_{PN}$
Vс	Supply voltage	+ 5 V				Supply voltage range±5%
Ιc	Current consumption	≤15mA				Reference will be subject to the measured
R1	Load impedance	≥10KΩ				Collection port impedance while lower voltage affect accuracy
Voe	Zero offset voltage	$\leq \pm 15 \mathrm{mV}$				TA=25℃
Tr	Response time	≤5 μ s				Reference will be subject to the measured
N.w	Weight	53g				Reference will be subject to the measured
Ta	Operation temperature	$-10$ $\sim$ $+70$ $^{\circ}$ C				
Ts	Storage temperature	$-25$ $\sim$ $+70$ $^{\circ}$ C				
Bw	Band width	DC~10KHz				Factory test according to DC
Vd	Delectric strength	2.5KV 50Hz 1min				

#### Factory commissioning:

Calculation formula: 2.5V±1.25V 0V datum

- 1. Debugging with 0V as the reference point(acquiescence) Forward direction:  $2.5 + (1/I_{pN}) *1.25$
- 2. Debug with Vref as the reference point(optional) Reverse direction:  $2.5-(1/I_{pN})*1.25$

## Instructions for use:

- 1. According to the connection mode of correct connection
- 2. The direction shown by the arrow is positive
- 3. With hole measurement, response time and following the speed for the best
- 4. Faulty wiring can lead to product damage and output uncertainty

#### Safe operation:

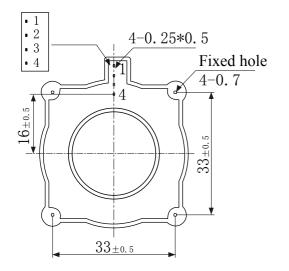
- \*Please read this specification carefully before use.
- \*When you need to move the product, please be sure to disconnect the power and all the connected cables.
- \*If found shell, devices attached to the fixed parts, wire, or have any damaged, please immediately deal with hidden dangers.
- \*If there is any doubt about the safe operation of the equipment, the equipment and the corresponding accessories should be closed immediately, and the fastest time for troubleshooting.

#### Proclamations:

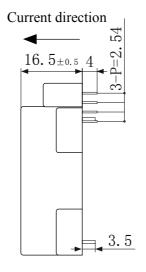
As our products are constantly being improved and updated, we reserve the right to modify the content of this specification at any time without prior notice.



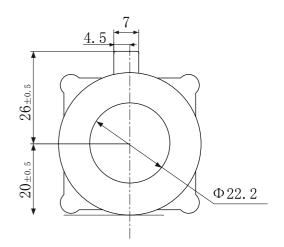
### Dimensions(in $mm\pm0.5$ ):



Bottom view

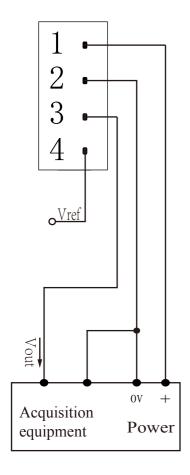


Side view



Top View

## Wiring diagram (based on 0 V)



## Pin definition:

1: +V

2: 0V

3: Vout

4: Vref (It can be suspended, not grounded)

## X Detection:

- ①Choose the auxiliary power supply with small ripple ( $\leq 10 \text{mV}$ )
- ②Switch on auxiliary power
- ③The auxiliary power is connected to the sensor
- 4) The sensor detects the primary current