

Hall open loop current sensor

Sub-plate mount, terminal output. Detect DC, AC and pulse current, high insulation between primary side and the vice side circuit.







Front view

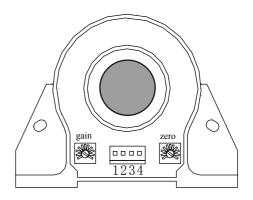
Epoxy view

Fixed hole view

Product features

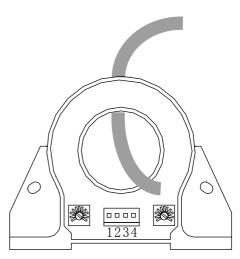
- ·Light weight
- •Low power consumption
- Good linearity
- •No insertion loss
- Fast response time
- Good anti-interference ability

Installation diagram



Product application

- Railway
- Metallurgical
- •Welding machine
- Robot
- Motor
- •Inverter power supply
- Variable frequency governor
- •Uninterrupted power supply and communication power supply





Electrical parameters: (The following parameters are typical values and actual values will be subject to product testing)

Remarks:

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I_{PN}	Rated input	±100A	±200A	±300A	±400A	± 500 A	$\pm 600A$	Standard input
Ipm	Input measurement range	± 150 A	$\pm 300 A$	$\pm 450 \mathrm{A}$	$\pm 600 A$	±750 A	$\pm 900 A$	Default is 1.5 times of rated input, and maximum ≤1000A (saturation)
Vout	Rated output		$2.5V \pm 0.625V$					Standard output
X	Accuracy			1	%	$I = I_{PN}$		
εL	Linearity	1%						$I=0^{\sim} \pm I_{PN}$
Vс	Supply voltage	+5V						Supply voltage range±5%
Ιc	Current consumption			≤1	2 m A	Reference will be subject to the measured		
R1	Load impedance	≥10KΩ						Collection port impedance while lower voltage affect accuracy
Voe	Zero offset voltage	\leq \pm 15 m V						TA=25°C
Tr	Response time	≤5 μ s						Reference will be subject to the measured
N.w	Weight			21	5g	Reference will be subject to the measured		
Ta	Operation temperature	-10 ∼ $+70$ °C						
Ts	Storage temperature	-25 ∼ $+70$ °C						
Bw	Band width			DC~1	0KHz	Factory test according to DC		
Vd	Delectric strength	6KV 50Hz 1min						

Factory commissioning:

Calculation formula: 2.5V±0.625V 0V datum

1. Debug with 0V as the reference point(acquiescence)

Forward direction: 2.5+ (I/I_{PN}) *0.625

2. Debug with Vref as the reference point(optional)

Reverse direction: $2.5-(I/I_{PN})*0.625$

Instructions for use:

- 1. According to the connection mode of correct connection
- 2. The direction shown by the arrow is positive
- 3. With hole measurement, response time and following the speed for the best
- 4. Faulty wiring can lead to product damage and output uncertainty

Safe operation:

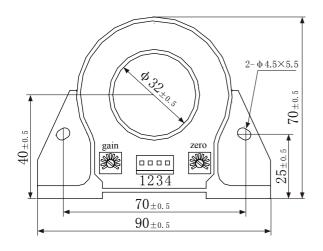
- *Please read this specification carefully before use.
- *When you need to move the product, please be sure to disconnect the power and all the connected cables.
- *If found shell, devices attached to the fixed parts, wire, or have any damaged, please immediately deal with hidden dangers.
- *If there is any doubt about the safe operation of the equipment, the equipment and the corresponding accessories should be closed immediately, and the fastest time for troubleshooting.

Proclamations:

As our products are constantly being improved and updated, we reserve the right to modify the content of this specification at any time without prior notice.



Dimensions(in mm±0.5):



6 76. 8±0.5 2. 4

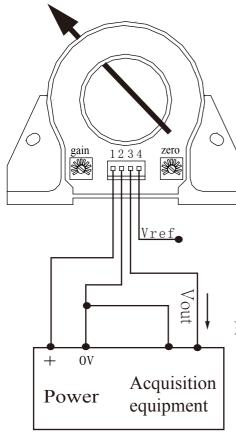
Fixed hole
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Front view

Bottom view

Wiring diagram (based on 0 V)



Connector Illustration:



Spacing 2.54 mm

Terminal definition:

1: +V

2: 0V

3: Vout

4: Vref

Potentiometer definition:

Left: gain

Right: zero

X Detection:

- ①Choose the auxiliary power supply with small ripple ($\leq 10 \text{mV}$)
- ②Switch on auxiliary power
- 3The auxiliary power is connected to the sensor
- 4 The sensor detects the primary current